



Robust Output LQ Optimal Control via Integral Sliding Modes (Systems & Control: Foundations & Applications)

Leonid Fridman, Alexander Poznyak, Francisco Javier Bejarano Rodríguez

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Featuring original research from well-known experts in the field of sliding mode control, this book presents new design schemes for a useful and practical optimal control with very few impractical assumptions. The results presented allow optimal control theory to grow in its applicability to real-world systems. On the cutting-edge of optimal control research, this book is an excellent resource for both graduate students and researchers in engineering, mathematics, and optimal control.

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